

# Machine Automation Controller

NX1P





# Advanced motion control and networks

# EtherNet/IP

Open industrial Ethernet network

- · Interface with HMI
- Peer-to-Peer controller communication
- Interface with Sysmac Studio
- Information network (host application)



## SD memory card

 Back up, restore, and verify data in the controller



## Option board

Add serial communications or analog control without increasing the size

- RS-232, RS-422A/485 (Modbus-RTU: 32 nodes max.)
- · Analog I/O



# Ether CAT.

The fast machine network for a wide range of field and motion devices.



#### Battery-free NX1P and 1S

The NX1P requires no battery to retain user program, set values, and variables during power interruption in the built-in memory.

The 1S AC Servo System comes with a battery-free absolute encoder.

They reduce machine maintenance.

# Advanced motion control increases machine speed and precision

The NX1P provides advanced motion control which previously would require a dedicated controller or special unit. Continuous operation by use of electronic cams improves productivity and meets diverse production needs.













# for onsite IoT in a compact controller



# Advanced motion control

# Built in EtherCAT and advanced motion control make machines faster and more precise

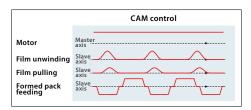
- EtherCAT simplifies the wiring to up to eight servo systems including for single-axis position control.
- Up to four axes of motion control. Increase machine speed and precision with electronic cams and interpolation.

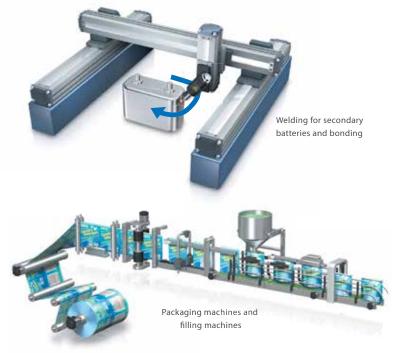
## Interpolation

• Precise machining and high-speed handling with Linear and circular interpolation

### Electronic cam

- High-speed and continuous machine operation using electronic cams
- Meet diverse production needs by using electronic cams instead of mechanical cams









# Networks for onsite IoT

# IO-Link brings IoT to the sensor level

- EtherCAT connects I/O devices, motion devices, safety controllers, and vision systems with a single cable. You can check machine information by monitoring the status of the connected components.
- EtherNet/IP enables communications with a host PC and data links between NJ/NX Controllers and CJ PLCs.

#### **Sysmac Automation Platform** Big data The Sysmac Studio integrates programming, configuration, and monitoring, reducing debugging and tuning times Controller Controller HMI EtherNet/IP Controller Factory NX1P Machine automation Programmable network Automation Automation Terminal Controller Controller NX1P Machine Automation EtherCAT. Controller Real-time Motion I/O Safety Vision machine network **IO**-Link 1S Servo System MX2 Inverter NX I/O IP67 I/O NX Safety FH Vision System Intelligent sensing Sensing Photoelectric Photoelectric sensor sensor

# Predictive maintenance using IO-Link

With the controller's IO-Link connectivity, you can implement predictive maintenance that lets you visualize machine status at the sensor level.



Proximity sensor Proximity sensor

# Product line up

### Machine Automation Controller NX-series

NX1P2 CPU Units





Ether CAT.

Dimensions (Unit: mm)

24-point type

130(W)×100(H)×71(D)

40-point type

154(W)×100(H)×71(D)

Option **Boards** 



Serial Communications NX1W-CIF01/ CIF11/CIF12



Analog I/O NX1W-ADB21/ DAB21V/MAB221

## NX Series Up to eight NX Units can be connected to an NX1P2 CPU Unit.



Digital I/O

Units

Analog I/O Units NX-AD/DA



Load Cell Input NX-RS



Communications Interface NX-CIF





**IO**-Link





SYSMAC-SE2



Sysmac Studio provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX CPU Units, EtherCAT Slave, and the HMI.

- Fully compliant with open standard IEC 61131-3 and Japanese standard
- Supports Ladder, Structured Text and Function Block programming with a rich instruction set
- CAM editor for easy programming of complex motion profiles
- One simulation tool for sequence and motion in a 3D environment
- · Advanced security function with 32 digit security password

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# Ordering Information

#### International Standards<sup>†</sup>

- The standards are abbreviated as follows: UC1: cULus (Class I Division 2 Products for Hazardous Locations), CE: EU Directives, RCM: RCM mark, and KC: KC Registration.
- · Contact your OMRON representative for further details and applicable conditions for these standards.

## **NX1P2 CPU Units**

Product name	Program capacity	Memory capacity for variables	Maximum number of used real axes			Total number of built-in I/O points			Model	Standards <sup>†</sup>
				Motion control axes**	Single-axis position control***		Number of input points	Number of output points		
40-point		32 KB	8 axes	4 axes	4 axes	40 points	points	16 points, NPN transistor	NX1P2-1140DT	UC1, CE, RCM,
	1.5MB	(Retained during power interruptions) and 2 MB (Not retained during power interruptions)						16 points, PNP transistor *	NX1P2-1140DT1	
			6 axes	2 axes	4 axes			16 points, NPN transistor	NX1P2-1040DT	
								16 points, PNP transistor *	NX1P2-1040DT1	
24-point			4 axes	0 axes	4 axes	24 points	14 points	10 points, NPN transistor	NX1P2-9024DT	
								10 points, PNP transistor *	NX1P2-9024DT1	

Note. One NX-END02 End Cover is provided with the NX1P2 CPU Unit.

- \*\*Motion control axes includes:
  - Point to point positioning
     Synchronized motion (Gearing/Camming)
  - Multi-Axes coordinated motion (Circular/Linear Interpolation)

- \*\*\*Single-axis position control includes:
- Only Point to point positioning
   No Synchronized motion (Gearing/Camming)
- No Multi-Axes coordinated motion (Circular/Linear Interpolation)
- No Axes grouping

# **Option Boards (For CPU Units)**

Product name	Specification	Supported protocol	Model	Standards
Serial Communications Option Board	One RS-232C port. Transmission distance: 15 m. Connection type: Screwless clamping terminal block (9 terminals).		NX1W-CIF01	
Serial	One RS-422A/485 port. Transmission distance: 50 m.  Connection type: Screwless clamping terminal block (5 terminals)  Host link, Modbus-RTU master, and no-protocol		NX1W-CIF11	
Communications Option Board	One RS-422A/485 port (isolated). Transmission distance: 500 m. Connection type: Screwless clamping terminal block (5 terminals)	and no protocor	NX1W-CIF12	
Analog Input Option Board	Analog input: 2 Voltage input: 0 to 10 V (Resolution: 1/4,000). Current input: 0 to 20 Connection type: Screwless clamping terminal block (5 terminals)	NX1W-ADB21	UC1, CE, RCM, KC	
Analog Output Option Board	Analog output: 2 Voltage output: 0 to 10 V (Resolution: 1/4,000) Connection type: Screwless clamping terminal block (3 terminals)	NX1W-DAB21V		
Analog I/O Option Board	Analog input: 2/Analog output: 2 Voltage input: 0 to 10 V (Resolution: 1/4,000). Current input: 0 to 20 Voltage output: 0 to 10 V (Resolution: 1/4,000) Connection type: Screwless clamping terminal block (8 terminals)	NX1W-MAB221		

## **Automation Software Sysmac Studio**

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include DVD.

Product name	Specification	Number of licenses	Media	Model
Sysmac Studio Standard Edition Ver.1.□□	Sysmac Studio runs on the following OS: Windows 7 (32-bit/64-bit version)/Windows 8 (32-bit/64-bit version)/ Windows 8.1 (32-bit/64-bit version)/Windows 10 (32-bit/64-bit version) The Sysmac Studio Standard Edition DVD includes Support Software to set up EtherNet/IP Units, DeviceNet slaves, Serial Communications Units, and Support Software for creating screens on HMIs (CXDesigner). For details, refer to the Sysmac Integrated Catalog (Cat. No. P072).	 (Media only)	DVD	SYSMAC-SE200D
3/15		1 license *	_	SYSMAC-SE201L

<sup>\*</sup> Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

<sup>\*</sup> With the load short-circuit protection.



#### OMRON AUTOMATION AMERICAS HEADQUARTERS • Chicago, IL USA • 847.843.7900 • 800.556.6766 • www.omron247.com

OMRON CANADA, INC. • HEAD OFFICE

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- Power Supplies Timers Counters Programmable Relays
- Digital Panel Meters Monitoring Products

#### **Switches & Relays**

- Limit Switches Pushbutton Switches Electromechanical Relays
- Solid State Relays

#### Software

• Programming & Configuration • Runtime

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