

CANopen

## Absolute Encoders – Multiturn

#### Standard, optical, electronical multiturn

## Sendix F5868 / F5888 (Shaft / Hollow shaft)



The Sendix F58 Multiturn with patented Intelligent Scan Technology™ is a particularly high resolution optical multiturn encoder without gears and with 100 percent magnetic insensitivity.

32 bits total resolution, through hollow shaft up to 15 mm and **CANopen functionalities according to up-to-date Encoder Profile.** 































Multiturn Resolution

Safety-Lock<sup>TM</sup>

High rotational speed

range

level

capacity

resistant

proof

protection

version on request

#### Reliable and insensitive

- Sturdy bearing construction in Safety Lock™ Design for resistance against vibration and installation errors
- · Ideal for use outdoors thanks to IP67 protection and wide temperature range from -40°C up to +80°C
- Patented Intelligent Scan Technology™ with all singleturn and multiturn functions on one single OptoASIC - offering the highest reliability, a high resolution up to 32 bits and 100% magnetic field insensitivity.

## **Up-to-the-minute Fieldbus performance**

- · CANopen with current encoder profile
- · LSS services for configuration of the node address and haud rate
- · Variable PDO mapping in the memory
- · Universal Scaling Function
- 32 bits total resolution (16 bit MT + 16 bit ST)

# Order code **Shaft version**

8.F5868 Type

**000** 

If for each parameter of an encoder the **underlined preferred option** is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days



a Flange

1 = clamping flange, ø 58 mm, IP65 2 = synchro flange, ø 58 mm, IP65

3 = clamping flange, ø 58 mm, IP67 4 = synchro flange, ø 58 mm, IP67

Shaft (ø x L), with flat

1 = 6 x 10 mm 1) 2 = 10 x 20 mm<sup>2)</sup>

 $3 = 6.35 \times 22.2 \text{ mm} (1/4" \times 7/8")$ 

 $4 = 9.5 \times 22.2 \text{ mm} (3/8" \times 7/8")$ 

© Interface / Power supply 2 = CANopen DS301 V4.2, 10 ... 30 V DC Type of connection

A = 1 x cable PVC, radial, length 2 m

E = 1 x M12 connector, radial F = 2 x M12 connector, radial

e Fieldbus profile 5)

21 = CANopen Encoder-Profil DS406 V3.2

Options (Service)

2 = no option

3 = SET button

optional on request

- Ex 2/22

- seawater-resistant

- special cable length

# Order code **Hollow** shaft

8.F5888

X|X|2|X|**a b e d** 

21 | 2 | X 0 then the delivery time will be 10 working days for a maximum of 10 pieces. Ots. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

1 = with torque stop set, IP65

2 = with torque stop set, IP67

3 = with stator coupling, ø 65, IP65 4 = with stator coupling, ø 65, IP67

5 = with stator coupling, ø 63, IP65 6 = with stator coupling, ø 63, IP67

**b** Hollow shaft

 $3 = \emptyset 10 \text{ mm}$ 

 $4 = \emptyset 12 \text{ mm}$ 

 $5 = \emptyset 14 \text{ mm}$  $6 = \emptyset 15 \text{ mm}$ 

B = Ø 12 mm, blind hollow shaft 3)

© Interface / Power supply 2 = CANopen DS301 V4.2, 10 ... 30 V DC **d** Type of connection

E = 1 x M12 connector, radial

F = 2 x M12 connector, radial 4)

L = 1 x cable PVC, tangential, length 2 m

e Fieldbus profile 5)

21 = CANopen Encoder-Profil DS406 V3.2

Options (Service)

2 = no option

3 = SET button

optional on request

- Fx 2/22
- seawater-resistant
- special cable length

Preferred type only in conjunction with Flange type 2

Preferred type only in conjunction with Flange type 1

Can be combined only with type of connection F Can be combined only with blind hollow shaft ø12 mm

CAN parameters can also be factory pre-set



# **Absolute Encoders – Multiturn**

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Mounting a	accessory for shaft encoders			
Coupling		Bellows coupling ø 19 mm for shaft 6 mm Bellows coupling ø 19 mm for shaft 10 mm	8.0000.1101.0606 8.0000.1101.1010	
Mounting a	accessory for hollow shaft encoders			
<b>Cylindrical</b> for torque stop	- Sw7	With fixing thread	8.0010.4700.0000	
Connection	ı technology			
Connector, self-assembly (straight)		Coupling M12 for Bus in Connector M12 for Bus out	8.0000.5116.0000 8.0000.5111.0000	
Cordset, pre	e-assembled with 2 m PVC cable	Bus in Bus out	05.00.6091.A211.002M 05.00.6091.A411.002M	
Programmi	ing set			
including:	- Interface converter USB-CAN - Connection cable from interface converter to en Power supply 90 250 V AC - DVD with Ezturn® software	Minimum System Requirements:  Operating system: Windows XP SP3 or high Win7 - 32 bit Win7 - 64 bit, in preparatio Processor: 1 GHz RAM: 512 MB Required disk space: 500 MB		

Mechanical characteristics				
Max. speed, shaft version without shaft seal (IP65) up to 70°C without shaft seal (IP65) up to T <sub>max</sub> with shaft seal (IP67) up to 70°C with shaft seal (IP67) up to T <sub>max</sub>	12 000 min <sup>-1</sup> , 10 000 min <sup>-1</sup> (continuous) 8 000 min <sup>-1</sup> , 5 000 min <sup>-1</sup> (continuous) 11 000 min <sup>-1</sup> , 9 000 min <sup>-1</sup> (continuous) 8 000 min <sup>-1</sup> , 5 000 min <sup>-1</sup> (continuous)			
Max. speed, hollow shaft version without shaft seal (IP65) up to 65°C without shaft seal (IP65) up to 75°C with shaft seal (IP67) up to 65°C with shaft seal (IP67) up to 75°C Starting torque, without shaft seal (IP65				
shaft version	< 0.01 Nm			
hollow shaft version	< 0.03 Nm			
Starting torque, with shaft seal (IP67)	< 0,05 Nm			
Moment of inertia Shaft version Hollow shaft version	3.0 x 10 <sup>-6</sup> kgm <sup>2</sup> 6.0 x 10 <sup>-6</sup> kgm <sup>2</sup>			
Load capacity of shaft radial axial	80 N 40 N			
Weight	approx. 0.45 kg			
Protection housing side acc. to EN 60529 shaft side	IP67 IP65, opt. IP67			
Ex approval for hazardous areas	optional Zone 2 and 22			
Working temperature range	-40°C +80°C <sup>1)</sup>			
Materials shaft / hollow shaft flange housing cable	stainless steel aluminium zinc die-cast housing PVC			
Shock resistance acc. EN 60068-2-27	2500 m/s², 6 ms			
Vibration resistance acc. EN 60068-2-6	100 m/s², 55 2000 Hz			

General electrical characteristics					
Power supply	10 30 V DC				
Current consumption (no load)	max. 80 mA				
Reverse polarity protection of the power supply $(\ensuremath{U}_B)$	yes				
UL approval	File 224618				
RoHS compliant acc. to	EU guideline 2002/95/EC				
CE compliant acc. to	EN 61000-6-2, EN 61000-6-4 and EN 61000-6-3				

Interface characteristics CANopen					
Singleturn resolution	1 65536 (16 bit), scaleable: 1 65536				
Default value Singleturn	8192 (13 bit)				
Gesamtauflösung	1 4.294.967.296 (32 bit) Default: 25 bit				
Code	Binary				
Interface	CAN High-Speed acc. to ISO 11898, Basic- and Full-CAN, CAN Specification 2.0 B				
Protocol	CANopen Profil DS406 V3.2 mit hersteller- spezifischen Ergänzungen, LSS-Service DS305 V2.0				
Baud rate	10 1000 kbit/s (software configurable)				
Node address	1 127 (software configurable)				
Termination switchable	software configurable				
LSS Protocol	CIA LSS protocol DS305, Global command support for node address and baud rate. Selective commands via attributes of the identity object				

Diagnostic LED (two-colour, red/green)					
LED ON or blinking		Error display Status display			
combination r	·	' '			



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**CAN**open

General information about CAN/CANlift

The CANopen encoders support the latest CANopen communication profile

according to DS301 V4.2. In addition, device specific profiles such as encoder profile DS406 V3.2 and DS305 (LSS) are available.

The following operating modes may be selected: Polled Mode, Cyclic Mode, Sync Mode and a High Resolution Sync Protocol. Moreover, scale factors, preset values, limit switch values and many other additional parameters can be programmed via the CAN bus.

When switching the device on, all parameters, which have been saved on an EEPROM to protect them against power failure, are loaded again.

The following output values may be combined in a freely variable way as PDO (PDO mapping): **position**, **speed**, **temperature** as well as the **status of the working area**.

The encoders are available with a connector or a cable connection.

The device address and baud rate can be set/modified by means of the software.

The two-colour LED located on the back indicates the operating or fault status of the CAN bus, as well as the status of the internal diagnostics.

#### **CANopen Communication Profile DS301 V4.2**

Among others, the following functionality is integrated. Class C2 functionality:

- NMT Slave
- Identity Object
- · Error Behaviour Object
- Variable PDO Mapping self-start programmable (Power on to operational), 3 Sending PDO's
- Node address, baud rate and CANbus / Programmable termination
- Producer / Consumer Heartbeat

#### **CANopen Encoder Profile DS406 V3.2**

The following parameters can be programmed:

- · Event mode
- 2 working areas with 2 upper and lower limits and the corresponding output states
- Variable PDO mapping for position, speed, work area status, error message, raw data
- Extended failure management for position sensing
- · User interface with visual display of bus and failure status
- Customer-specific memory 16 Byte
- · Customer-specific protocol
- Universal Scaling Function (USF)
- · "Watchdog controlled" device
- · Extended diagnostic modes

#### LSS Layer Setting Services DS305 V2.0

- · Global support of Node-ID and baud rate
- Selective protocol via identity object (1018h)

#### **Universal Scaling Function**

At the end of the physical resolution of an encoder, **when scaling is active**, an error appears if the division of the physical limit (GP\_U) by the programmed total resolution (TMR) does not produce an integer.

The Universal Scaling Function remedies this problem.

### Terminal assignment

Interface	Type of connection	Function	unction Cable						
			Signal:	0 V	+V	CAN_Low	CAN_High	CAN	
				power supply	power supply	(-)	(+)	Ground	
2	A, L	Bus IN	Abbreviation:	0 V	+V	CL	СН	CG	
			Cable colour:	WH	BN	YE	GN	GY	
Interface	Type of connection	Function	2 x M12 conne	ectors					
			Signal:	0 V	+V	CAN_Low	CAN_High	CAN	2 1
		Bus IN			power supply	(-)	(+)	Ground	2 <b>7.3</b>
		Dus IIV	Abbreviation:	0 V	+V	CL	СН	CG	
2	F		Pin:	3	2	5	4	1	4 5
			Signal:	CAN	CAN_Low	CAN_High	0 V	+V	1 - 2
				Ground	(-)	(+)	power supply	power supply	
		Bus OUT	Abbreviation:	CG	CL	CH	0 V	+V	3
			Pin:	1	5	4	3	2	5 4
Interface	Type of connection	Function	1 x M12 conne	ector					
			Signal:	0 V	+V	CAN_Low	CAN_High	CAN	2 1
				power supply	power supply	(-)	(+)	Ground	
2	E	Bus IN	Abbreviation:	0 V	+V	CL	СН	CG	3 + ( • • • )

2

5

3

Pin:



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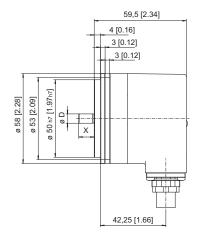
**CANopen** 

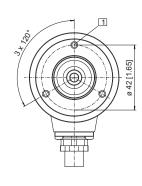
#### **Dimensions shaft version**

Synchro flange, ø 58 mm Flange type 2 and 4

(Drawing with M12 connector)

1 3 x M4, 6 [0.24] deep



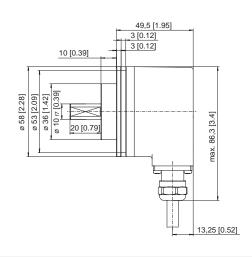


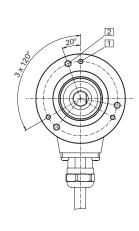
#### Clamping flange, ø 58 mm Flange type 1 and 3

(Drawing with cable outlet)

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep

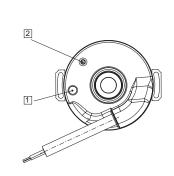


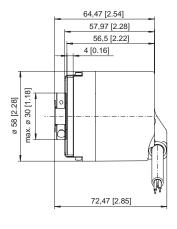


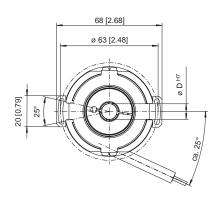
#### **Dimensions hollow shaft version**

#### Flange with stator coupling, $\emptyset$ 58 mm Flange type 5 and 6

Pitch circle diameter for fixing screws 63 mm (Drawing with tangential cable outlet)







1 Status-LED

2 SET button

Dimensions in mm [inch]